

## Motivation

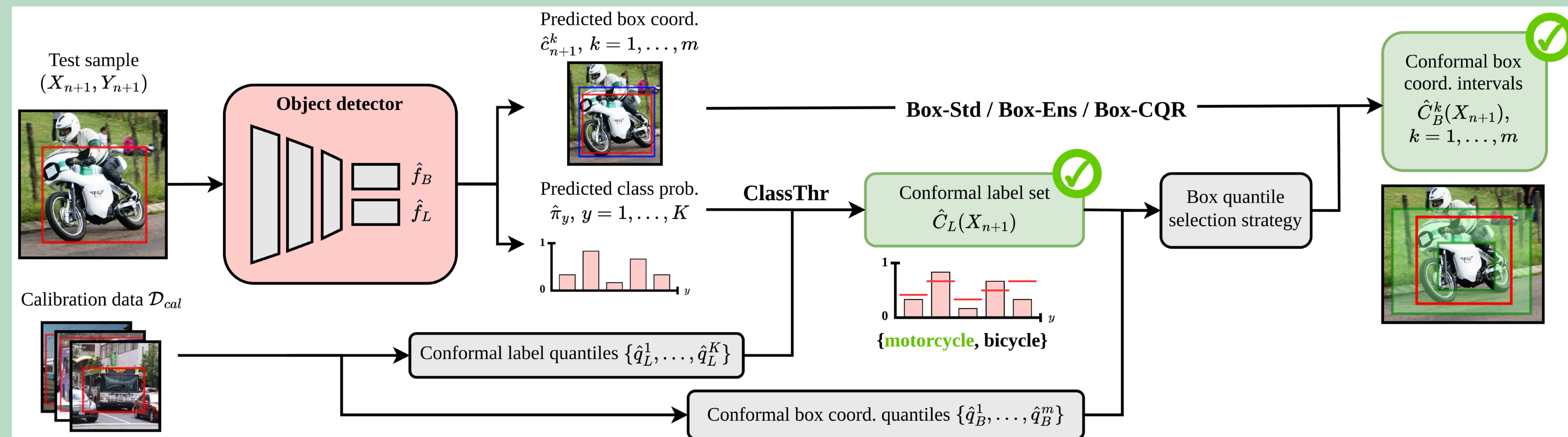
Autonomous agents should be able to reliably and efficiently quantify their predictive uncertainty to make safer decisions when relying on real-time bounding box predictions.

- Problem #1: How to obtain reliable bounding box uncertainties, and in what form?
- Problem #2: Object detectors predict an object's class label and its box coordinates. Both tasks exhibit uncertainty that needs to be accounted for.
- Solution (TLDR): Employ post-hoc, distribution-free conformal prediction in two steps to provide bounding box prediction intervals with coverage guarantees.



## Two-Step Conformal Prediction

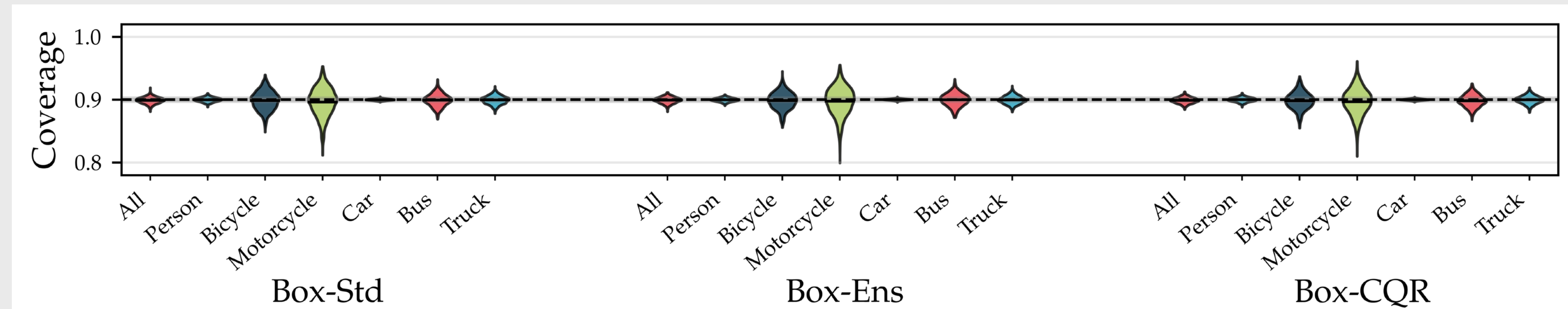
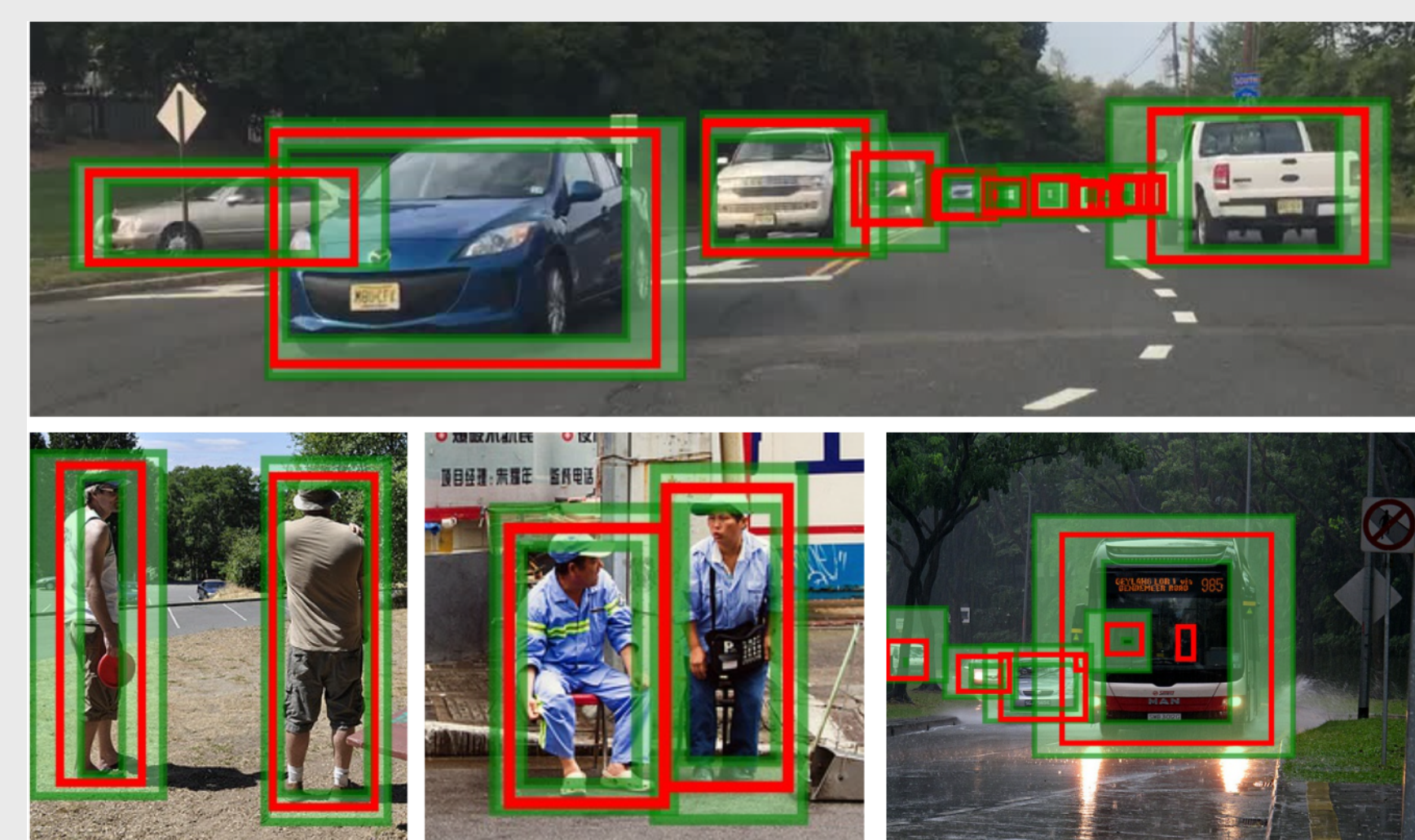
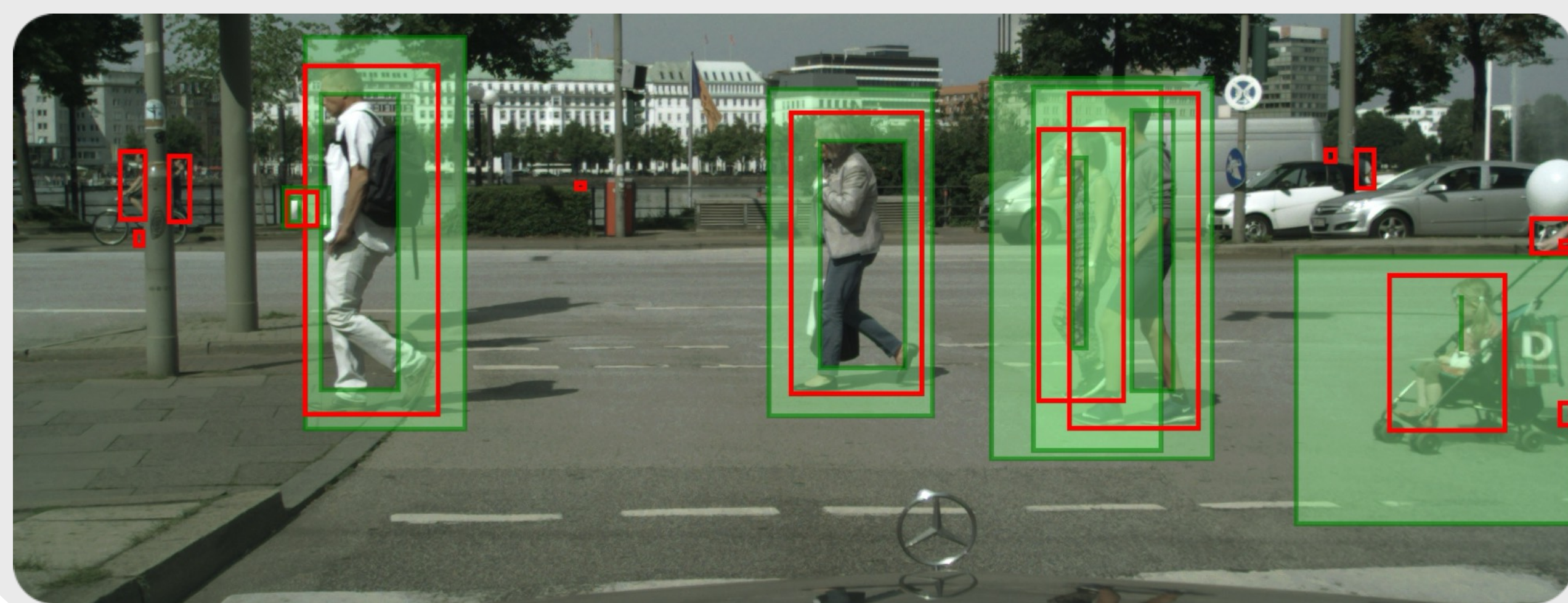
- STEP 0**
- Precompute conformal quantiles on  $\mathcal{D}_{cal}$ .
  - Pass test sample through object detector.
- STEP 1**
- Apply conformal classification (ClassThr) to class probabilities to get a label set.
- STEP 2**
- Apply conformal regression and use label set from Step 1 to build final prediction intervals for bounding box coordinates.



Our coverage guarantee: For exchangeable (iid) calibration data  $\mathcal{D}_{cal}$  and test sample  $(X_{n+1}, Y_{n+1})$  where  $Y = (c^1, c^2, c^3, c^4, l)$ , it holds that:  $\mathbb{P} \left( l_{n+1} \in \hat{C}_L(X_{n+1}) \wedge \bigcap_{k=1}^m (c_{n+1}^k \in \hat{C}_B^k(X_{n+1})) \mid l_{n+1} = y \right) \geq (1 - \alpha_L)(1 - \alpha_B) \approx (1 - \alpha_B) \quad \forall y \in \mathcal{Y}$

## Results

- Bounding box intervals are tight and scale adaptively with class instances.
- Guarantees hold across object classes, datasets, and 'black-box' models.



## References

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- Angelopoulos & Bates (2023). Conformal prediction: A gentle introduction (F&T in ML)
- Romano et al. (2019). Conformalized Quantile Regression (NeurIPS)
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